Teledyne SeaBotix

LBV200-4

Little Benthic Vehicle



Sets the Standard for MiniROV Capability

The SeaBotix LBV200-4 ROV is an extremely stable and highly maneuverable platform - the most capable and adaptable system of its size.

This original benchmark ROV has 4-axis maneuverability via powerful brushless DC thrusters and is supplied with a choice of intuitive and rugged control consoles.

The LBV200-4 offers a range of sensor and tooling choices which include HD video, scanning, imaging and profiling sonar, tracking system, grabber and cutting tool plus many other options; and so provides a turnkey solution for a wide range of demanding applications and challenging situations.

The LBV200-4 is depth rated to 200 m (660 ft) and is supplied with tether and storage reel complete with integrated slip ring, a choice of high resolution video cameras and LED lighting plus depth, heading and temperature sensors.

The vehicle can also be supplied as part of a fly-out package to operate from a manned-submersible, Work Class ROV or tracked trencher, etc.

Offered with a 2-year limited manufacturer's warranty, 24/7 technical support and after-sales service from factory staff or authorized international service centers.







PRODUCT FEATURES

LBV200-4 MINIROV

- 4-Axis Maneuverability
- 200 Meter (660 ft) Depth Rating
- Powerful Brushless DC Thrusters
- 180° Camera Tilt
- High Intensity LED Tracking Camera
- Flexible Sensor Platform
- Integrated Control Console
- Small Diameter Low Drag Tether
 8.9 mm (0.35 in) Nominal

LBV200-4 MiniROV

- Integrated Control Console
- Tether/Reel
- Spares/Tools/Manuals
- Transit Cases

LBV200-4 System Components





TECHNICAL SPECIFICATIONS

LBV200-4 MINIROV SYSTEMS

| | IFD | ۱ı |
|-----|------|-----|
| ULL | IFK# | AI. |

| Depth Rating | 200 m (660 ft) |
|---------------|------------------|
| Length | 530 mm (21 in) |
| Width | 245 mm (9.65 in) |
| Height | 254 mm (10 in) |
| Weight in Air | 11 kg (24.3 lbs) |

THRUSTERS | PERFORMANCE

| Configuration | 2 forward, 1 vertical, 1 lateral |
|------------------|---|
| Motor Type | Brushless DC direct drive |
| Bollard Thrust | Forward - 7 kgf (15.4 lbf) Lateral - 3 kgf (6.6 lbf) Vertical - 3 kgf (6.6 lbf) |
| Speed at Surface | 3 knots (1.54 m/sec) |

CAMERAS | LIGHTING

| Camera | 680 line high resolution color |
|-------------|---|
| Camera Tilt | 180 degrees |
| Focus | Manual (90 mm to infinity) |
| Format | NTSC or PAL |
| Lighting | Internal 700 Lumen LED array, tracks color camera |
| | |

| Control System | |
|-------------------|---|
| Configuration | Single rugged case w/monitor, OCU & power supply |
| Monitor | 38 cm (15 in) LCD |
| Power Requirement | 1,200 Watts, 100-130/200-260 VAC |
| Safety | Isolated input, circuit breaker, LIM, leak monitoring |
| Auto Functions | Depth, heading, trim |
| Video Overlay | Depth, heading, lights, thruster gain, turns counter, camera angle, time, date & user |

Tether | Reel

| Diameter | 8.9 mm (0.35 in) nominal | |
|-------------------|---|--|
| Length | 250 m (820 ft) standard, 350 m (1,148 ft) max. | |
| Working Load | 100 kgf (220 lbf) | |
| Breaking Strength | 700 kgf (1,543 lbf) | |
| Buoyancy | Neutral in fresh water, slightly positive in seawater and other options available | |
| Reel | Heavy duty w/slip ring | |

programmable characters



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Options

| Tether Lengths | Up to 350 m (1,148 ft) |
|----------------|---|
| Grabber | Three jaw, interlocking small, interlocking large, parallel and cutter |
| Sonars | Imaging, scanning, profiling |
| Tracking | USBL positioning system |
| Lights | Ultra bright LED (tracking camera) |
| Console | Integrated Navigation/Control Console |
| Other | HD and zoom cameras, UT and CP sensors, water samples, laser scaling and more |









Setting the Standard for MiniROV Capability

- · Outstanding capability and value for money
- Powerful brushless DC direct drive thrusters
- High resolution color, monochrome and HD video options
- · Industry leading low drag tether
- Extensive range of optional sensors and tooling
- Turnkey inshore/offshore solution



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